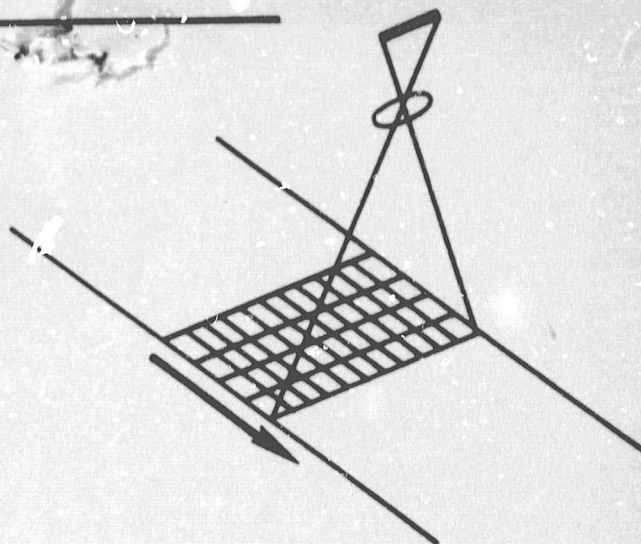


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MRS

**LITERATURE SURVEY
OF
ATMOSPHERIC CORRECTIONS**

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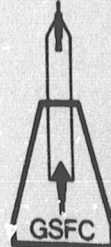
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NASA—
GODDARD SPACE FLIGHT CENTER
GREENBELT, MD. 20771

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MULTISPECTRAL RESOURCE SAMPLER

"PROOF OF CONCEPT"

LITERATURE SURVEY OF
ATMOSPHERIC CORRECTIONS

PREPARED FOR
NATIONAL AERONAUTICS & SPACE ADMINISTRATION
GODDARD SPACE FLIGHT CENTER
GREENBELT, MARYLAND 20771

TABLE OF CONTENTS

	Page
I INTRODUCTION	1.0
II LITERATURE SURVEY AND REVIEW OF ATMOSPHERIC EFFECTS IN REMOTE SENSING AND THEIR INFLUENCE ON CLASSIFICATION	2.0
2.0 INTRODUCTION.	2.1
2.1 ATMOSPHERIC EFFECTS ON CLASSIFICATION	2.2
2.2 DETAILED REVIEW OF SELECTED PAPERS.	2.5
2.3 SUMMARY	2.18
2.4 LITERATURE SURVEY	2.19
2.5 ALPHABETICAL COMPUTER PRINT-OUT BIBLIOGRAPHY.	2.21
2.6 CHRONOLOGICAL COMPUTER PRINT-OUT BIBLIOGRAPHY.	2.37

I. INTRODUCTION

The Multispectral Resource Sampler "Proof-of-Concept" Study is intended to be a comprehensive analysis of the corrections that must be applied to MRS data to allow for atmospheric correction factors and the variability of bidirectional reflectance from the scene.

In order to assess the present state-of-the-art in these areas a literature review and analysis was initiated at the outset of the study. The reviews and analyses which are included have been compiled by:

DR. James A. SmithBIDIRECTIONAL REFLECTANCE
MR. Kenneth J. RansonBIDIRECTIONAL REFLECTANCE

DR. Philip N. SlaterATMOSPHERIC CORRECTIONS
DR. Robert A. SchowengerdtATMOSPHERIC CORRECTIONS

Their efforts include short descriptions of the more pertinent papers and bibliographies of the materials which have been reviewed.

The two Literature Surveys, Bidirectional Reflectance and Atmospheric Corrections, have been published under separate covers for ease of reference.

II

Literature Survey and Review
of Atmospheric Effects in Remote Sensing
and Their Influence on Classification

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Committee on Remote Sensing

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September, 1979

PREFACE

This report is divided into five sections.

The introduction refers 1) to work done in combining spectral bands to reduce atmospheric effects on spectral signatures, 2) to the development of atmospheric models and their use with ground and aerial measurements in correcting spectral signatures, 3) to other methods of making such corrections, and 4) to some second order atmospheric effects.

The second section of the report provides an overview of studies of atmospheric effects on the accuracy of scene classification.

The third section describes some of the more important publications selected from the previous section, summarizing the results in graphical and tabular form.

The fourth section summarizes the results reported in the previous sections and suggests aspects of the work that merit further study.

The fifth section mentions the various sources referred to in the literature survey that were used to produce the alphabetical and chronological listing of 59 entries.

2.0 INTRODUCTION

While a very large amount of research on atmospheric properties, models, and measurements has been reported in the physics, optics, and meteorological literature, the emphasis in this survey is on work related to remote sensing of the earth's surface from aircraft and spacecraft. Much of the pioneering atmospheric research was done at the Environmental Research Institute of Michigan in connection with airborne multispectral scanners. It was soon realized that the effects of atmospheric variations along a flight path, from one date to another, and as a function of scanner look angle were severely limiting development of reliable classification procedures for multispectral data.

One of the first approaches to alleviating atmospheric problems (and other sources of variability such as scanner calibration shifts and changes in sun angle) was the application of various combinations of spectral band differences and ratios (Crane, (1971), Kriegler, et al (1969)). The work of Horvath, et al (1970) studied the apparent ground radiance as a function of aircraft altitude and derived sensor signal-to-noise ratios as a function of altitude for both electro-optical and photographic systems.

At the same time as the development of these empirical techniques was accelerating, there were parallel efforts in development of atmospheric models (Potter (1969), Turner, et al (1971)). Improvements in atmospheric models and their application have been made by Herman & Browning (1975), Turner (with Spencer (1972), (1975), (1977), (1978)) and Fraser ((1974, et al (1977)). Models which permit direct estimation of aerosol content in the atmosphere from Landsat imagery of water bodies have also been developed (Griggs (1973, 1974) and, Mekler, et al (1977)).

Because of the requirement of many models from ancillary ground or aerial measurements (Rogers and Peacock (1973), Hulstrom (1975), Dana (1975, 1978)), there has been continuing interest in atmospheric correction techniques which utilize only information available in the imagery itself. One of the most widely used techniques involves measurement of the darkest (minimum radiance)

pixels in the image (Potter and Mendolowitz(1975) and Chavez, (1975)). Other approaches require deep water bodies, such as lakes, within the image (Rochon, et al (1978)). One of the difficulties with such techniques is that turbidity caused by rain, wind, etc. can alter lake spectral signatures (Erb (1974)). Some atmospheric correction techniques are intimately related to classification procedures by comparison of training and study area spectral signatures followed by corrective transformations (Henderson (1975), Lambeck and Rice (1976)).

There has been research into some of the secondary atmospheric problems, such as the influence of pixel neighborhood radiance variations on the apparent pixel radiance (Turner (1975), Buznikov, et al (1975), Pearce (1977), Kawata et al (1978), Otterman and Fraser (1979)). The thermal spectral regions has also received attention (Boudreau (1972), Kumar (1977)).

2.1 ATMOSPHERIC EFFECTS ON CLASSIFICATION

There has been surprisingly little investigation of the effects of the atmosphere on classification accuracies. One of the first examples is the work of Nalepka and Morgenstern (1972). This study showed considerable improvement in agricultural signature extension of airborne multispectral scanner data after application of band-to-band ratios and an average signal versus scan angle normalization, both examples of the self-correction approach. Rogers, et al (1973, third ERTS-1 Symposium) simulated atmospheric changes in transmittance and path radiance in a single Landsat scene and classified the data with a fixed (originally correct) set of training signatures. Parametric curves of classification accuracy for eight urban and rural classes were generated as a function of change in atmospheric transmittance (path radiance fixed) and in path radiance (transmittance fixed). Accuracies for signature extension over a four month period were also reported. An improved classification was obtained of a March scene using April training signatures and a transformation of variables using data from a ground radiometer but no accuracy figures were given.

Pitts, et al (1974) simulated the effect of an increase in atmospheric water vapor on an agricultural classification. The cause of classification degradation in this case was absorption of radiation in band 7 of Landsat, which can be simply modeled as a multiplicative factor in band 7 alone. Pitts, et al, determined that training in low humidity areas to classify relatively high humidity areas was preferable to the reverse situation.

Turner (1975, NASA report) simulated an atmospheric scattering gradient over a regular pattern of simulated corn and soybean fields. The gradient varied from a visual range of 23 km at one end of the pattern (also the visual range of the training data) to 13 km and 8 km at the other end. In the former case the corn classification accuracy decreased by 1.4% while the soybean accuracy increased by 2%. This is an example of the complex interaction between atmospheric scattering and spectral signatures of surface features. Generally, the overall recognition accuracy decreased very little for these scattering gradients.

Potter (1974) used a similar set of actual Landsat data of corn and soybean fields. A set of five spatially uniform simulated atmospheres with optical depths of 0.1, 0.2, 0.3, and 0.4 were applied to this data with no retraining for spectral signatures the accuracies for both corn and soybeans remained within 3% up to an optical depth of 0.1 and decreased rapidly for greater haze levels. As expected from theoretical predictions, if retraining is performed, the atmospheric conditions are uniform, and there are no neighborhood interactions Potter's data showed virtually no effect on classification accuracy up to an optical depth of 0.4. He also reproduced similar results to the "train low, test high" results of Pitts et al (1974). One interesting effect noticed in Potter's data is the strong (negative) effect thresholding of the classification has when combined with increased haze levels.

Fraser (1977) applied an atmospheric scattering gradient, measured from Landsat over a portion of the Atlantic Ocean near Africa, to another Landsat scene of Pennsylvania. The intent was to apply a realistic, large area gradient

in a controlled manner. As Fraser points out, the spatial and temporal correlations of atmospheric properties have not been determined in continental regions. The unmodified Landsat data of Pennsylvania was clustered in an unsupervised mode into ten classes. The modified data, created by addition of the atmospheric gradient, were also clustered and compared to the clusters of the unmodified data. Changes in class means and variances were tabulated. A maximum likelihood classification was then performed using both sets of training clusters. Without retraining 22% of the pixels changed classification from the original unmodified classification. With retraining, only 3% changed classifications. The net change in turbidity simulated was 1.3 between the modified and unmodified data sets.

A comparison of performance among several signature extension algorithms was reported by Abotteen, et al (1977). Two sets of data were used, one a simulated set of normally-distributed agricultural crops and the other seven pairs of consecutive-day passes over an agricultural area. The authors found little difference in performance among the algorithms but in almost all cases the signature extension approach was less accurate than retraining.

2.2 DETAILED REVIEW OF SELECTED PAPERS

A useful reference to representative values of atmospheric quality for urban, suburban and rural conditions has been provided by Flowers et al (1969), they reported the results of a five-year study of atmospheric turbidity measurements from a network of stations in the U.S. The following general conclusions were drawn from the study: 1) an annual mean pattern of turbidity across the U.S. was noted that varied from a low of near 0.05 over the western plains and Rocky Mountains to a high of near 0.14 in the east; 2) the observed minimum value of turbidity was near 0.02; 3) an annual cycle exists of low turbidity in winter and high in summer; 4) lowest turbidity conditions occur for continental polar air masses and highest turbidity occurs under maritime tropical conditions; 5) there is no noticeable lowering of turbidity following precipitation.

The turbidity coefficient, B , used by Flowers et al is the decadic extinction coefficient at a wavelength of $0.5 \mu\text{m}$ and is related to the often-used atmospheric optical depth, τ , by $B = 2.3\tau$. τ is often quoted for $\lambda = 0.55 \mu\text{m}$ whereas B was determined at $\lambda = 0.5 \mu\text{m}$. The effect of the change in wavelength depends on the atmospheric particle-size distribution, however, as a first approximation $\tau_{0.55} = 0.9 \tau_{0.5}$. The plot of Flowers et al of the cumulative frequencies of the daily average turbidity for typical urban, suburban and rural conditions is presented in tabular form in Table 1 in terms of optical depth (recall that the optical depth, τ , in the table is for a wavelength of $0.5 \mu\text{m}$). Note that 95% of the days in rural areas have τ values of less than 0.3 which corresponds to a visibility or meteorological range of about 25 km.

TABLE 1
PERCENT OF DAYS WITH HAZE LEVEL IN INDICATED RANGE

Lower bound for τ	0	0.1	0.2	0.3	0.4
Upper bound for τ	0.1	0.2	0.3	0.4	∞
Rural	10	65	20	4	1
Suburban	7	28	35	12	18
Urban	2	13	15	15	55

Potter (1974) and Potter and Shelton (1974) studied the effect on classification accuracy of changes in atmospheric conditions. They simulated various haze levels by adding values of 0.1, 0.2, 0.3 and 0.4 to a given atmospheric condition to provide a table of multispectral scanner responses in counts corresponding to these haze levels. This table was used to transform the input data in LARSYS format to data corresponding to the simulated haze level also in LARSYS format.

The effect of the addition of simulated haze was to increase the number of counts and to decrease or compress the range of response. As an extreme example, Potter and Shelton show graphically that the addition of an optical depth of 0.8 increases the number of counts for MSS band 4 from 0 (in the no haze case) to 20 and at the same time decreases the total response range for band 4 from 127 to 107 counts.

Two crop types, corn and soybeans were studied by the authors. The initial statistics were obtained from a Landsat data set obtained over an area in Illinois in which about two thirds of the planted farmland contained these crops. It was assumed for this analysis that this data set represented a target without haze. The effect of an increasing haze level is shown in Tables II and III.

TABLE II.
MEANS, μ , AND STANDARD DEVIATIONS, σ , FOR CORN

Haze Level		0.0	0.1	0.2	0.3	0.4
Channel 1 }	μ	22.00	24.00	26.00	27.66	29.10
	σ	1.38	1.16	1.16	0.88	1.01
Channel 2 }	μ	15.22	15.21	16.22	18.21	19.96
	σ	1.11	1.08	1.11	1.08	0.85
Channel 3 }	μ	46.95	47.94	48.01	48.94	49.86
	σ	4.92	4.84	4.83	4.83	4.72
Channel 4 }	μ	30.35	30.35	30.35	30.36	30.77
	σ	3.47	3.47	3.47	3.46	3.15

TABLE III
MEANS, μ , AND STANDARD DEVIATIONS, σ , FOR SOYBEANS

Haze Level	0.0	0.1	0.2	0.3	0.4
Channel 1 } μ σ	23.11 1.27	25.11 1.27	27.09 1.21	28.42 0.97	30.13 1.23
Channel 2 } μ σ	13.68 1.66	15.66 1.61	16.68 1.69	18.66 1.61	20.24 1.40
Channel 3 } μ σ	61.97 11.45	62.49 11.05	63.02 11.33	63.51 11.00	64.17 11.10
Channel 4 } μ σ	38.56 8.04	38.56 8.04	38.56 8.04	38.60 7.94	38.70 7.80

Note how the means, μ , increase and the standard deviations, σ , in general decrease as the τ values increase. (The cases where the σ values decrease result from the quantization of the response). Note also how the changes are much more pronounced for the shorter wavelengths because Rayleigh and aerosol scattering both increase with decreasing wavelengths for the model used.

If the addition of a uniform haze layer over the training and test areas causes a linear transformation of the data, then the presence of haze will have no effect on classification accuracy. The results in Table IV substantiate this conclusion.

TABLE IV
CLASSIFICATION ACCURACIES FOR UNIFORM HAZE LEVELS

Haze Level	0.0	0.1	0.2	0.3	0.4
CORN	97.4	97.5	97.4	97.5	97.4
SOYBEANS	99.0	99.2	99.0	99.2	98.2

A minimal amount of thresholding was used; in all cases the thresholding used to yield the 97.4% and 99% values in the first column. The variations in the values in the table are due to quantization effects.

The effects on classification accuracy of a haze level that changed from training site to test site were next explored. The training site was first assumed to have zero haze (see Table V). The same input data for corn and soybeans was used as before but in this case two threshold levels were used.

TABLE V
CLASSIFICATION ACCURACIES FOR TRAINING ON ZERO HAZE

Test Haze Level		0.0	0.1	0.2	0.3	1
CORN	Low Thresholding	97.4	93.6	56.1	1.8	0.0
	Moderate Thresholding	94.6	79.1	12.9	0.0	0.0
SOYBEANS	Low Thresholding	99.0	96.4	70.7	28.0	0.0
	Moderate Thresholding	95.0	82.1	23.7	1.0	0.0

The low threshold level in Table V is the same as that used in Table IV, the moderate level is more typical of that used in practice. There are several points of interest:

1. Up to a haze level of 0.1 there is a relatively small effect.
2. For values of $\tau > 0.1$ there is a rapid decrease in classification accuracy.
3. The rate of decrease in accuracy depends on the threshold level, the decrease being more rapid with moderate than with low thresholding.
4. The effect for soybeans is smaller than that for corn.

This last point can probably be explained by the narrower distribution of the corn data. As the authors point out, if the standard deviation does not change, a classification based on data from one band decreases in accuracy as

a monotonically increasing function of a single variable, $\Delta \mu / \sigma$, where $\Delta \mu$ is the change in the mean, σ , due to the addition of haze. Tables 2 and 3 show that for all four bands, $\Delta \mu / \sigma$ is larger for corn than for soybeans mainly because of the smaller value for σ . Because $\Delta \mu / \sigma$ decreases very rapidly as the spectral bands go to longer wavelengths, it is probable that bands 4 and 5 account for most of the effect.

Pitts et al (1974) showed that classification accuracy was higher for the case of training under clear atmospheric conditions and testing under hazy conditions than vice versa. Potter and Shelton verified this conclusion using the same statistics for corn and soybeans as before. Table VI summarizes their results. The first column of numbers is a repeat of the corresponding column in Table V to show the levels of thresholding used. The next two columns show the effects of training at a low haze level and testing at a high level and vice versa. Clearly the "train low, test high" sequence gives the better results and the low thresholding is preferred. The last two columns are for training with $\tau = 0$ and testing with $\tau = 0.3$ and vice versa. As expected the decrease in accuracy is even more marked in this case. (The low thresholding result follows the tendency of the $\tau = 0.2$ results, the moderate thresholding does not, however, the accuracies are so low as to be susceptible to errors induced by quantization.)

TABLE VI
CLASSIFICATION ACCURACY

TABLE VI. CLASSIFICATION ACCURACY.

Test Haze Level	0.0	0.2	0.0	0.3	0.0
Train Haze Level	0.0	0.0	0.2	0.0	0.3
CORN } Low Thresholding	97.4	56.1	49.5	1.8	0.5
	94.6	12.9	7.8	0.0	0.1
SOYBEANS } Low Thresholding	99.0	70.7	59.4	28.0	4.8
	95.0	23.7	15.7	1.0	1.0

It should be noted that the results of Pitts et al were due to compression of the data. The Potter and Shelton results were mainly additive with little compression. For symmetrical data there should be no difference between training high and testing low and vice versa. The results in Table VI are therefore attributable to a skew in the data. If this is true, then Potter and Shelton suggest that no general statement can be made as to whether or not it is better to train low and test high.

The effect on clustering of using reflectance values instead of uncorrected digital values from the original data is shown in Figures 1 and 2. The clustering of uncorrected data, taken over a period of many months is shown in Figure 1, due to Paris (1974). The plot is of band 5 MSS values against band 7 MSS values, note the considerable overlap of the data. Correcting the data for τ and zenith angle variations results in data values more characteristic of the features of interest. In Figure 2, Paris shows that the clusters are more clearly separated, resulting in a more accurate classification.

Turner (1975) simulated a variable atmosphere in which the visual range was first changed from 23 km to 13 km across the scene and each data point was modified according to the particular atmospheric conditions chosen. First, corn and soybean fields under the clearer atmosphere were used as the training fields in the classification procedure. The percentage of correctly classified areas changed slightly from 87.6% and 87.1% for a uniform atmosphere to 86.2% and 89.1% for the variable case for corn and soybeans respectively. (Note that for soybeans the accuracy increased). Second, using values from the entire scene, instead of only the clearest conditions, the classification accuracy remained about the same at 87.6% for corn and 87.8% for soybeans.

Turner summarized his results in the form of histogram plots of the number of fields with a given classification accuracy, Figure 3. As the change in atmospheric haze becomes more pronounced, the histogram has a greater spread and the accuracy of classification for corn decreases from 87.6% to 83.6%.

Abotteen et al (1977) conducted comparative tests on seven signature extension algorithms to determine their effectiveness in correcting for changes in atmospheric haze and sun angle. Four of the algorithms (OSCAR, MOD OSCAR,

Figure 1. Landsat 1 Gray Scale Units of Coastal

Features in MSS Bands 5 and 7 (Paris, 1974)

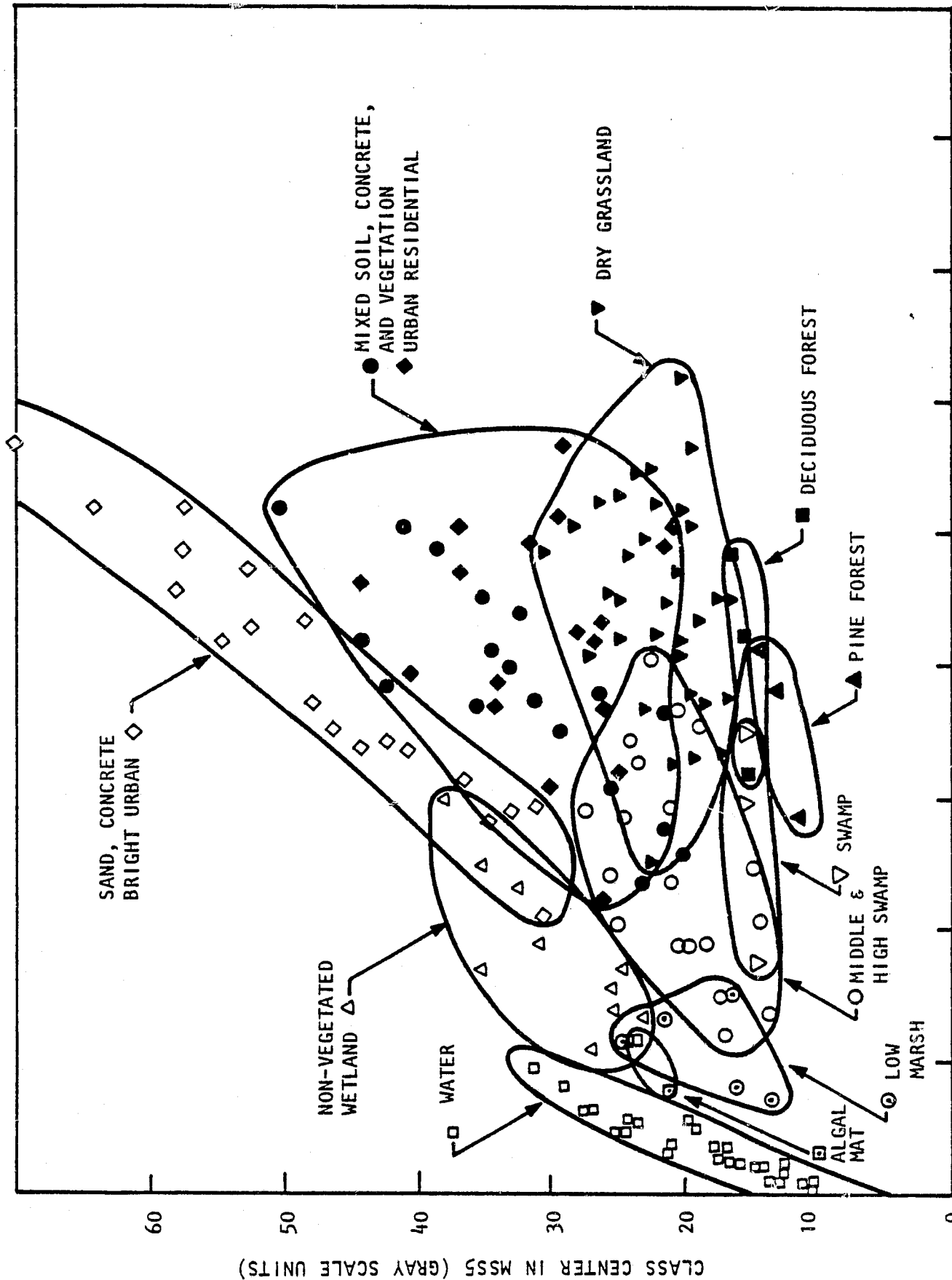
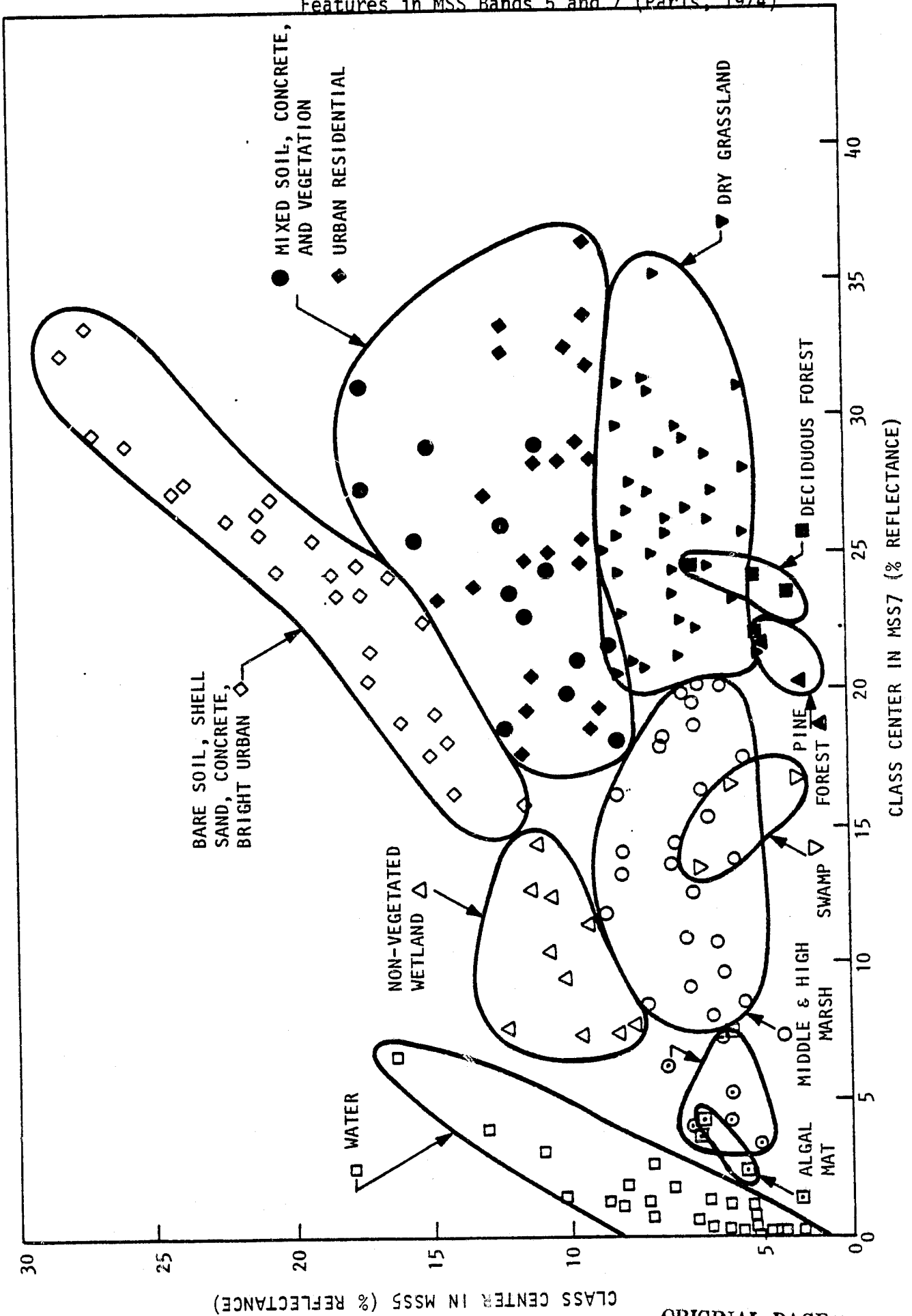
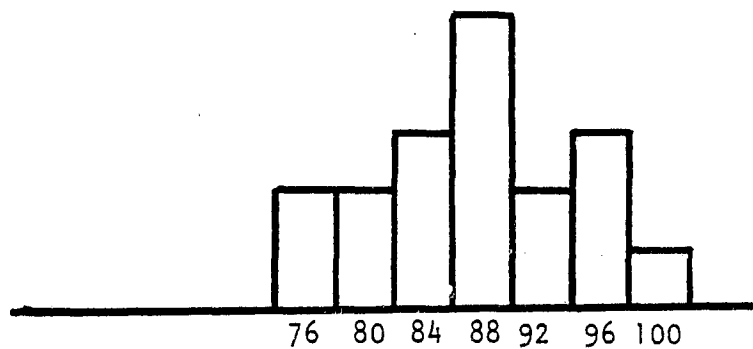


Figure 2. Landsat-1 Reflectance Signatures of Coastal Features in MSS Bands 5 and 7 (Paris, 1974)

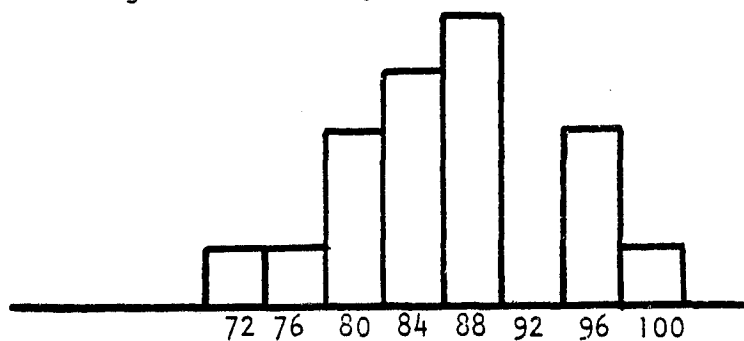


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OF POOR QUALITY

Case 1: Uniform atmosphere, $V = 23$ km
Mean recognition = 87.6%



Case 2: Non-uniform atmosphere, $13 \leq V \leq 23$ km
Mean recognition = 86.2%



Case 3: Non-uniform atmosphere, $8 \leq V \leq 23$ km
Mean recognition = 83.6%

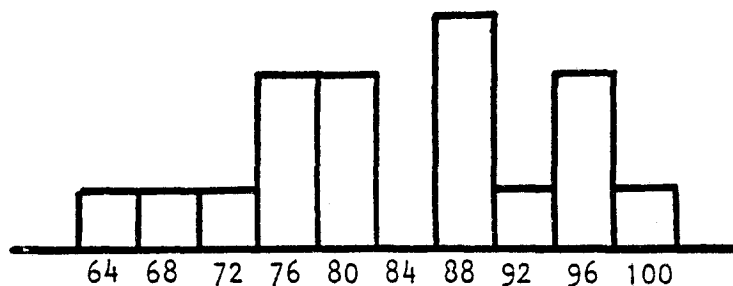


FIGURE 3. Number of fields versus classification accuracy Turner (1975).

ROOSTER & MOD ROOSTER) were cluster matching, two were maximum likelihood (MLEST & UHMLE) and the last (ACTOR) determined the haze level in the training and test areas and used a set of tables from an atmospheric model to correct the training signatures. Simulated and consecutive-day data were used in the comparison. The simulated data were obtained from means and covariance matrices determined from four passes of two training areas in Montana. An algorithm was used to generate multivariate normal data with the same statistics. This was done separately for the four passes of the first area. Then each pass of the second area was created from the distributions used in the corresponding pass of the first area by transforming them with an affine transformation so that the data corresponded to a different sun angle. The data for the first area were used as the training data and the data for the second area were used for the test area. All classifications were made in four bands. The consecutive-day data were from seven sets of consecutive-day Landsat-1 passes over test sites in Kansas. Ground truth was available for all fields in all the test areas. A subset was selected for training fields, and fields were grouped into subclasses with the aid of cluster maps. A signature extension area was defined in each site that included a ground-truth area in each case. The approach was to make signature extension runs using the above mentioned algorithms and to compare the results with local classification results or ground truth. The algorithms were to provide modified training statistics which then were used to classify the test areas. The UHMLE algorithm computed these modified statistics directly; all the other algorithms computed an affine transformation that was then used to modify the training statistics.

The results of the study are summarized in Table VII. The first two columns list the algorithms in the order in which they performed in the accuracy test for simulated and consecutive-day imagery and the numbers listed are the mean percentage differences between the accuracy obtained using the algorithms and local accuracy. (The minus sign indicates that the algorithm was less accurate than local classification.)

TABLE VII

SUMMARY OF TEST RESULTS

Percentage difference between local accuracy and that obtained with various algorithms				Wheat proportions difference from local				Wheat proportion difference from ground truth			
Simulated data		Consecutive-day data		Simulated data		Consecutive-day data		Simulated data		Consecutive-day data	
R(S)	0.0	R(S)	-1.6	R(S)	0.2	R(S)	2.7	R(S)	0.8	UH all	8.6
MLEST	-1.7	MLEST	-1.8	R(C)	1.3	REGRES	3.3	R(C)	1.1	REGRES	9.8
UH fields	-7.1	OSCAR	-2.4	MLEST	2.4	OSCAR	3.6	MLEST	3.0	UH all MLE	10.0
R(C)	-9.4	REGRES	-2.8	UH fields MLE	5.0	MOD R	3.8	UH fields MLE	4.9	R(S)	10.0
UT	-44.1	MOD R	-2.8	UH fields	6.4	UT	4.1	UH fields	6.3	ATCOR	10.5
		R(C)	-3.7	UT	13.5	MLEST	4.2	UT	12.8	OSCAR	10.8
		MOD OSCAR	-3.8			ATCOR	4.3			MOD R	11.2
		ATCOR	-4.3			MOD OSCAR	4.8			R(C)	11.3
		UH fields	-5.1			R(S/C)	5.2			MLEST	11.7
		UT	-6.6			R(C)	6.4			MOD OSCAR	11.7
		R(S/C)	-7.1			UH all	12.8			UH fields	12.6
		UH all	-10.6			UH fields	13.2			UT	12.9
						UH all MLE	13.6			R(S/C)	14.9

A statistical analysis of the accuracy results for the consecutive-day data (except for the three versions of UHMLE which were omitted because of large variances) indicated:

1. No significant difference between the algorithms
2. Greater classification accuracy when the training was done on the hazier site, this was in contrast to the test site being hazier than the training site or when the atmosphere over both sites was clear.

The wheat proportion differences between ground truth and local results are listed in the last four columns of Table VII. The results show that the performance ratings for the algorithms are the same for simulated data but different for consecutive-day data. This was because local results were different from ground-truth results for the consecutive-day data. A statistical analysis of the consecutive-day data for wheat proportion differences from local results (with the omission of data from R(S/C), a variant of ROOSTER, and UHMLE because of large variances) revealed no significant differences between the algorithms tested. The best results were again for the case of training under hazy conditions. The three algorithms tested on the simulated data produced significant

improvements over the results obtained using untransformed signatures. For the consecutive-day data, the tested algorithms produced improvements in most but not all cases.

Fraser (1977) studied the effect of differences in atmospheric turbidity on the classification of Landsat MSS observations of a rural scene in Pennsylvania. The original observations were classified by an unsupervised clustering procedure, LARSYS Version 3. The resulting classes served as a training set for use with a maximum likelihood algorithm. From another Landsat image, of an area of the Atlantic Ocean just west of the Spanish Sahara, the differences in radiance were determined for two points 90 km apart over the deep ocean during a period of mild outflow of Sahara dust. This difference was subtracted from the Pennsylvania data and amounted to decreasing the atmospheric turbidity over the rural scene from 5.7 to 4.41, a decrease of 1.3 standard deviations for rural regions. (Note that the turbidity of the unmodified Pennsylvania scene of 5.7 is 2.8 standard deviations above the mean for the rural U.S. Fraser's experiment then simulates a reduction in turbidity from a large value of 2.8 to 1.5 standard deviations above the mean.) As shown in Table VIII, 22% of the pixels in the rural data, classified by the maximum likelihood algorithm, were changed as a result of the modification. The modified data were then reclassified but this time with the statistics of their own data and, as shown in Table IX, only 3% of the pixels in the two sets of data then had different classifications. Hence, if classification errors of rural errors are not to exceed 15%, a new training set has to be developed whenever the atmospheric turbidity changes by one standard deviation.

TABLE VIII

THE CLASSIFICATION MATRIX OF UNMODIFIED AND MODIFIED DATA
USING THE UNMODIFIED STATISTICS

<div> <div>Class</div> <div>Modified</div> <div>→</div> </div> <div>↓ Unmodified</div>	Number of pixels					Number of pixels in unmodified classification
	1-6	7	8	9	10	
1-6	750 (75.6) ^a	218 (22.0)	0	24 (2.4)	0	992
7	0	93 (30.8)	187 (61.9)	22 (7.3)	0	302
8	0	0	340 (68.0)	159 (31.8)	1 (0.2)	500
9	0	0	0	959 (100.0)	0	959
10	0	0	0	1 (2.1)	46 (97.9)	47
Number of pixels in modified classification	750	311	527	1165	47	Total = 2800

^aThe numbers in parentheses show the transition percentages of a class of unmodified pixels to the various classes of modified classification.

TABLE IX

THE CLASSIFICATION MATRIX OF UNMODIFIED AND MODIFIED DATA SETS
USING THEIR OWN STATISTICS, WHICH ARE INDEPENDENT FOR EACH OTHER

<div> <div>Class</div> <div>Modified</div> <div>→</div> </div> <div>↓ Unmodified</div>	Number of Pixels					Number of pixels in unmodified classification
	1-6	7	8	9	10	

2.3 SUMMARY

Several points can be made based on the research in this area:

- 1) Atmospheric changes are significant enough in many cases to make signature extension or retraining necessary
- 2) Although signature extension algorithms work generally quite well, retraining appears to be more accurate for multi-date imagery. The problem of normalizing spatially variable atmospheric conditions does not appear to have been addressed for satellite imagery.
- 3) The relatively few quantitative studies of atmospheric effects and their correction in the context of classification accuracies have yielded results which are not easily generalized. This fact arises from the complex and diverse nature of spectral signatures of interest. There appears to be a need for simple, conceptual experiments which could lead to a better understanding of the interactions underlying atmospheric effects on classification.
- 4) To underscore this last point, we should point out that, in spite of the results of the many studies reported here, we are still unable to predict in general the effect of a given change in atmospheric conditions on classification accuracy or the spectral signatures of commonly occurring ground features. (Potter's results show that a change in τ of 0.2 across a scene can catastrophically reduce classification accuracy. However, such a large change in τ is unlikely to occur often across a Landsat scene.) The most important recommendation resulting from this literature review is that a generalized study is needed, for commonly occurring surface features, of the changes in their spectral signatures and in the accuracy of their classification introduced by changes in τ of between 0 and 0.2.

2.4 LITERATURE SURVEY

Several computer bibliographic data bases were searched in compilation of the enclosed literature survey. They were:

EROS Data Center Remote Sensing Bibliography
Department of Energy Energy Information Data Base (RECON)
Department of Interior Office of Water Research and Technology
Water Resources Thesaurus, 2nd Edition (RECON)

In addition the proceedings of prominent professional symposia were reviewed. These included:

Proceedings of the International Symposium on Remote Sensing of
Environmental Research Institute of Michigan, 1969, 1971, 1972,
1974, 1975, 1977, 1978.

Proceedings of the Machine Processing of Remotely Sensed Data
Symposium, IEEE, 1973, 1975, 1976, 1977, 1979.

Proceedings of Society of Photooptical Instrumentation Engineers, SPIE.

Proceedings of the American Society of Photogrammetry, ASP.

Proceedings of the Symposium on Significant Results Obtained from
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Finally, the indices of two remote sensing journals were reviewed. They were:

Photogrammetric Engineering and Remote Sensing, ASP.

Remote Sensing of Environment, Elsevier North-Holland, Inc.

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